Introduction to Parallel programming distributed systems

- Parallel programming MPI/openMP/RMI ...
- Service Oriented Architecture and Web Service
- Grid computing
- Cloud Computing
- Workflow
- Discussions
BigData

• General introduction to BigData
• MapReduce and Beyond
• Analytics of BigData
• Technology for Big Data
If you know these concepts you are attending the wrong class …

- Supercomputing / High Performance Computing (HPC)
- Node
- CPU / Socket / Processor / Core
- Task
- Pipelining
- Shared Memory
- Symmetric Multi-Processor (SMP)
- Distributed Memory
- Communications
- Synchronization
- Granularity
- Observed Speedup
- Parallel Overhead
- Massively Parallel
- Embarrassingly Parallel
- Scalability
Content

- Computer Architectures
- High Performance Computing (HPC)
- Speed up
- Parallel programming models
Computer Architecture

- supercomputers use many CPUs to do the work
- All supercomputing architectures have
  - processors and some combination cache
  - some form of memory and input/output IO
  - the processors are separated from every other processors by some distance

- there are major differences in the way these parts are connected

- some scientific problems fit better some architectures better than others
• How CPU works [http://www.youtube.com/watch?v=cNN_tTXABUA](http://www.youtube.com/watch?v=cNN_tTXABUA)
• How Computers Add Numbers In One Lesson: [http://www.youtube.com/watch?v=VBDoT8o4q00&feature=fvwp](http://www.youtube.com/watch?v=VBDoT8o4q00&feature=fvwp)
• Computer Architecture Lesson 1: Bits and Bytes [http://www.youtube.com/watch?v=UmSelKbP4sc](http://www.youtube.com/watch?v=UmSelKbP4sc)
• Computer Architecture Lesson 2: Memory addresses [http://www.youtube.com/watch?v=yF_txERujps&NR=1&feature=episodic](http://www.youtube.com/watch?v=yF_txERujps&NR=1&feature=episodic)
• Richard Feynman Computer Heuristics Lecture [http://www.youtube.com/watch?v=EKWGGDXe5MA](http://www.youtube.com/watch?v=EKWGGDXe5MA)
Architectures: Michael J. Flynn (1972)

- Flynn’s taxonomy distinguish multi-processor computer according to independent dimensions
  - Instruction
  - Data

- Each dimension
  - Single
  - Multiple
Parallel Computer Memory Architectures

• we can also classify supercomputers according to how the processors and memory are connected

  – couple of processors to a single large memory address space

  – couple of computers, each with its own memory address space
Parallel Computer Memory Architectures

Shared Memory
- Uniform Memory Access (UMA)
- Non-Uniform Memory Access (NUMA)

Distributed Memory Multiprocessor
- Processors have their own local memory
- Changes it makes to its local memory have no effect on the memory of other processors.
Parallel Computer Memory Architectures

Shared Memory

- Uniform Memory Access (UMA)
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Distributed Memory Multiprocessor

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High Performance Computing

• increasing computing power available allows
  – increasing the problem dimensions
  – adding more particles to a system
  – increasing the accuracy of the result
  – improve experiment turnaround time
  – …
Why Use supercomputers?

- To solve larger problems
- To use non-local resources
- To save time and/or money
- Because they enable concurrency

DreamWorks Presents the Power of Supercomputing
http://www.youtube.com/watch?v=TGSRvV9u32M&feature=fvwp

https://computing.llnl.gov/tutorials/parallel_comp/
High Performance Computing

• What does *High-Performance Computing (HPC)* mean?
  – High-performance computing (HPC) is the **use** of **super computers** and **parallel processing techniques** for solving complex computational problems.

  – *HPC technology* focuses on **developing** parallel processing systems by incorporating both **administration** and **parallel computational** techniques.

  The terms **high-performance computing** and **supercomputing** are sometimes used interchangeably.

http://www.techopedia.com/definition/4595/high-performance-computing-hpc
Content

- High Performance Computing
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- Speed up
- Parallel programming models
- Example of Parallel programs
How can we measure how much faster our program runs when using more than one processor?

Define Speedup $S$ as:
- the ratio of 2 program execution times
- constant problem size
  - $T_1$ is the execution time for the problem on a single processor (use the “best” serial time)
  - $T_P$ is the execution time for the problem on $P$ processors

$$S = \frac{T_1}{T_P}$$
Speedup

• Linear speedup
• Sublinear speedup
• Superlinear speedup

• why do a speedup test?

Speedup: $S = \frac{T_1}{T_P}$
Speedup: Limit of Parallel programming

- A program **always** has a **sequential** part and a parallel part

```
(1) A = B+C;
(2) D = A + 1;
(3) E = D + A;
(4) For (I=0; I<E; I++)
(5) M(I) = 0;
```

- the best you can do is to sequentially execute 4 instructions no matter how many processors you get

http://www.docstoc.com/docs/2698537/Introduction-to-Parallel-Programming
Speedup: Implication

- Parallel programming is great for programs with a lot of parallelism
  - Jacobi, scientific applications (weather prediction, DNA sequencing, etc)
- Parallel programming may not be that great some traditional applications:
  - Computing Fibonacci series $F(K+2)=F(k+1) + F(k)$
Speedup: Amdahl’s Law (1967)

- Amdahl's Law states that potential program speedup is defined by the fraction of code (P) that can be parallelized:

\[
\text{speedup} = \frac{1}{1 - P}
\]

\[
\text{Parallel Portion of Code}
\]

Jon Johansson Academic ICT Copyright © 2006 University of Alberta
Speedup: Amdahl’s Law (1967)

- Introducing the number of processors performing the parallel fraction of work, the relationship can be modeled by:

\[
\frac{1}{\text{speedup}} = \frac{P + S}{N}
\]
Gustafson’s law

- Amdahl’s law assumes a constant problem size
- Now, let’s allow scaling of the problem size
- Gustafson’s law considers the execution time of a parallel program using \( n \) processors with a sequential fraction \( s \) (with \( s \) in \([0,1]\))

\[
\text{Speedup} = \frac{s + n(1-s)}{s + (1-s)}
\]

*Translates into:* Speedup = \( s+n(1-s) = n-s(n-1) \)
Content

• High Performance Computing
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• How to design Parallel programs
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• Example of Parallel programs
Design Parallel programs

• Domain decomposition and functional decomposition
  – Domain decomposition: DATA associate with a problem is decomposed.
    • Each parallel task then works on a portion of data
  – Functional deposition: focus on the computation that is be performed. The problem is decomposed according to the work that must be done.
    • Each task then performs a portion of the overall work
Data parallelism

Domain decomposition:

• Also Called data parallelism

• DATA associate with a problem is decomposed.

• Each parallel task then works on a portion of data

• Example: MapReduce

http://www.docstoc.com/docs/2698537/Introduction-to-Parallel-Programming
Data parallelism

Domain decomposition methods:

• Same datum may be needed by multiple tasks

• Decompose the data in such a manner that the required communication is minimized

• Ensure that the computational loads on processes are balanced

http://www.docstoc.com/docs/2698537/Introduction-to-Parallel-Programming
Data parallelism

Hierarchical work distribution

To solve this problem we designed a hierarchical work distribution algorithm that recursively splits the world into blocks (top-down).

Example:

Split each result into 32 (nodes)
Split each result into 16 (cores)

Maximize load balance and minimize communication at each level!

Source: A Distributed Approach to Improve the Performance of the Parallel Ocean Program
Ben van Werkhoven et al., Geoscientific Model Development, 7, 257–281, 2014

Jason Maassen
Functional deposition

• the focus is on the **computation** that is to be performed rather than on the data manipulated by the computation.

• The problem is decomposed according to the **work that must be done**.

• Each task then **performs a portion** of the overall work.
CESM model coupling

Data dependencies allow some models to run concurrently, while others must run in sequence.

(balancing their run times is black magic)

Atmosphere, land and sea ice exchange data every 30 model minutes, but ocean only 1x to 4x each model day!
Data Dependence

• A dependence exists between programs when the order of statement execution affects the results of the program.

• A data dependence results from multiple use of the same location(s) in storage by different tasks.

  (task 1) – (task 2)

  – True dependence: Write X – Read X
  – Output dependence: Write X – Write X
  – Anti dependence: Read X – Write X

Dependencies: are important to parallel programming because the are one of the inhibitors to parallelism.

http://www.docstoc.com/docs/2698537/Introduction-to-Parallel-Programming
Data Dependence

• The value of \( a(I-1) \) must be computed before the value of \( a(I) \).

• \( A(I) \) exhibits a data dependency on \( a(I-1) \).

• Parallelism is inhibited.

Data dependency examples

\[
\begin{align*}
\text{For } (I=0; I<500; i++) \\
a(I) &= 0;
\end{align*}
\]

\[
\begin{align*}
\text{For } (I=0; I<500; i++) \\
a(I) &= a(I-1) + 1;
\end{align*}
\]
Load balancing

- Distribute the **computation/communication** such that all the processor are busy all the time.
- At a synchronization point, the worst case performance is the real performance
Communications

• Parallel applications that do not need communications are called **embarrassingly parallel programs**
  – Monte carlo method, Seti at home
  – Most programs (e.g. Jacobi) are not like that
  – Communication is inherent to exploit parallelism in a program
Communications

• Factors to consider:
  – Cost of the communication
  – Latency and bandwidth
  – Synchronous and asynchronous
  – Point to point or collective
Overlapping communication and computation

- Make processors busy when waiting for communication results
  - Usually achieved by using non-blocking communicating primitives

Loading balancing, minimizing communication and overlapping communication with computation are keys to develop efficient parallel applications.
Some basic load balancing techniques

• Equally partition the work each task receives
  – For array/matrix operations where each task performs similar work, evenly distribute the data set among the tasks.
  – For loop iterations where the work done in each iteration is similar, evenly distribute the iterations across the tasks.

• Use dynamic work assignment
  – Sparse arrays
  – Adaptive grid method
  – If a heterogeneous mix of machines with varying performance
    → scheduler - task pool approach
Granularity

• Computation/ Communication
  – In parallel programming, granularity is a qualitative measure of the ratio of the computation to communication.

  – Periods of computation are typically separated from periods of communication by synchronization events
    • Computation phase and communication phase
Granularity

• Fine-grain parallelism
  – Relatively small amount of computational work are done between communication events

  Low computation to communication ratio implies high commutation overhead and less opportunity for performance enhancement

• Coarse-grain parallelism
  – Relatively large amounts of computation work are done between communication/synchronization events

  High computation to communication ratio implies more opportunity for performance increase Harder to load balance efficiently
Deadlock/Livelock

• Deadlock appears when two or more programs are waiting and none can make progress

• Livelock results from indefinite loop.
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Parallel Programming models

Data Parallelism/task parallelism
• Shared Memory (without threads/Threads)
• Distributed Memory / Message Passing

High level programming models
• Single Program Multiple Data (SPMD)
• Multiple Program Multiple Data (MPMD)

https://computing.llnl.gov/tutorials/parallel_comp/#ModelsOverview
Parallel programming

- need to do something to your program to use multiple processors
- need to incorporate commands into your program which allow multiple threads to run
  - one thread per processor
  - each thread gets a piece of the work

- several ways (APIs) to do this …
Parallel programming

Message Passing Interface (MPI)

- **Interprocess** communication which have separate address spaces

- Data is **explicitly** sent by one process and received by another
  - Data transfer usually requires cooperative operations to be performed by each process.
  - For example, a send operation must have a matching receive operation
Parallel programming

Message Passing Interface (MPI)

• What is MPI?
  – A message-Passing Library specification
  – Not a language or compiler specification
  – Not a specific implementation or product

• For parallel computers, clusters, and heterogeneous networks.
  – Designed to provide access to advanced parallel hardware for:
    • End users, library writers, tools developers

What is message passing?

• Data transfer plus synchronization
  • Requires cooperation of sender and receiver
  • Cooperation not always apparent in code
Parallel programming

Message Passing Interface (MPI)

• Why use MPI?
  – Optimized for performance
  – Will take advantage of fastest transport found
    • Shared memory (within a computer)
    • Fast cluster interconnects (Infiniband, Myrinet..) between computers (nodes)
  • TCP/IP if all else fails
Parallel programming

Message Passing Interface (MPI)

Deadlocks?

• Send a large message from proc A to proc B
  – If there is insufficient storage at the destination, the send must wait for the user to provide the memory space (through a receive)

• What will happen? (unsafe)
  – Process 0
    Send(1)
    Recv(1)
  – Process 1
    Send(0)
    Recv(0)
Parallel programming

Message Passing Interface (MPI)

- Very good for distributing large computations across reliable network

- Would be terrible for a distributed internet chat client or BitTorrent server

What is message passing?

- Data transfer plus synchronization
- Requires cooperation of sender and receiver
- Cooperation not always apparent in code
Example MPI Hello World

```c
#include <mpi.h>

int main(int argc, char** argv) {
    // Print off a hello world message
    printf("Hello world from processor ");
}
```
Threads

- threads model of parallel programming, a single process can have multiple, concurrent execution paths
- Each thread has local data, but also, shares the entire resources of executable a.out.
- Threads communicate with each other through global memory
Parallel programming

Open MultiProcessing (OpenMP)

- What is OpenMP?
  - is a library that supports parallel programming in shared-memory parallel machines.
  - allows for the parallel execution of code (parallel DO loop), the definition of shared data (SHARED), and synchronization of processes
Parallel programming

- Open MultiProcessing (OpenMP)
  - What is the programming model?
    - All threads have access to the same, globally shared, memory
    - Data can be shared or private
      - Shared data is accessible by all threads
      - Private data can be accessed only by the threads that owns it

Data transfer is transparent to the programmer
Synchronization takes place, but it is mostly implicit
Parallel programming

Open MultiProcessing (OpenMP)

- **OpenMP language extensions**
  - **parallel control structures**
    - governs flow of control in the program
    - *parallel* directive
  - **work sharing**
    - distributes work among threads
    - *do/parallel do* and *section* directives
  - **data environment**
    - *shared* and *private* clauses
  - **synchronization**
    - coordinates thread execution
    - *critical* and *atomic* directives
    - *barrier* directive
  - **runtime functions, env. variables**
    - runtime environment
    - *omp_set_num_threads()*
    - *omp_get_thread_num()*
    - OMP_NUM_THREADS
    - OMP_SCHEDULE
Example OpenMP Hello World

```c
#include <omp.h>
#include <stdio.h>
#include <stdlib.h>
int main (int argc, char *argv[]) {
    printf("Number of threads: ");
}
```

```bash
$ icc -o omp_hello -openmp omp_hello.o
omp_hello.o(22): (col. 1) remark: OpenMP DEFINED REGION WAS PARALLELIZED.
$ export OMP_NUM_THREADS=3
$ ./omp_hello
Hello World from thread = 0
Hello World from thread = 2
Hello World from thread = 1
Number of threads = 3
```
Parallel programming

Pros/Cons of OpenMP

- easier to program and debug than MPI
- directives can be added incrementally - gradual parallelization
- can still run the program as a serial code
- serial code statements usually don't need modification
- code is easier to understand and maybe more easily maintained

- can only be run in shared memory computers
- requires a compiler that supports OpenMP
- mostly used for loop parallelization

Pros/Cons of MPI

- runs on either shared or distributed memory architectures
- can be used on a wider range of problems than OpenMP
- each process has its own local variables
- distributed memory computers are less expensive than large shared memory computers

- requires more programming changes to go from serial to parallel version
- can be harder to debug
- performance is limited by the communication network between the nodes
Parallel programming

Shared State Models

- Views an application as a collection of processes communicating by putting/getting objects into one or more spaces

- A space is a shared and persistent object repository that is accessible via network

- The processes use the repository as an exchange mechanism to get coordinated, instead of communicating directly with each other

implementation: Java (JavaSpaces), Lisp, Prolog, Python, Ruby, and the .NET framework
Parallel programming

**Shared State Models:** Publish/Subscribe

- Publish/subscribe systems are programming capability provided by associative matching

- Allows the producers and consumers of data to coordinate in a way where they can be decoupled and may not even know each other’s identity
  - SOA, Web service etc.
Parallel programming

**RPC and RMI Models**

- **Structure the interaction** between sender and receiver as:
  - a language construct, rather than a library function call that simply transfers an uninterpreted data.

- provide a simple and well understood mechanism for managing remote computations
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calculations on 2-dimensional array elements

• The serial program calculates one element at a time in sequential order.
• Serial code could be of the form:

```plaintext
do j = 1,n
   do i = 1,n
      a(i,j) = fcn(i,j)
   end do
end do
```
calculations on 2-dimensional array elements: solution 1

• Implement as a Single Program Multiple Data (SPMD) model.
• each task executes the portion of the loop corresponding to the data it owns.

```fortran
  do j = mystart, myend
    do i = 1,n
      a(i,j) = fcn(i,j)
    end do
  end do
```
calculations on 2-dimensional array elements: implementation

• Implement as a Single Program Multiple Data (SPMD) model.

• Master process initializes array, sends info to worker processes and receives results.

• Worker process receives info, performs its share of computation and sends results to master.
calculations on 2-dimensional array elements: implementation

find out if I am MASTER or WORKER

if I am MASTER

initialize the array
send each WORKER info on part of array it owns
send each WORKER its portion of initial array

receive from each WORKER results

else if I am WORKER
receive from MASTER info on part of array I own
receive from MASTER my portion of initial array

# calculate my portion of array
do j = my first column, my last column
   do i = 1, n
      a(i,j) = fcn(i,j)
   end do
end do
end do

send MASTER results
endif

https://computing.llnl.gov/tutorials/parallel_comp/#MemoryArch
calculations on 2-dimensional array elements: solution 2

• Solution 1: demonstrated static load balancing:
  – Each task has a fixed amount of work to do
  – May be significant idle time for faster or more lightly loaded processors - slowest tasks determines overall performance.

• If you have a load balance problem (some tasks work faster than others),
  – you may benefit by using a "pool of tasks" scheme.

https://computing.llnl.gov/tutorials/parallel_comp/#MemoryArch
calculations on 2-dimensional array elements: solution 2

• Master Process:
  – Holds pool of tasks for worker processes to do
  – Sends worker a task when requested
  – Collects results from workers

• Worker Process: repeatedly does the following
  – Gets task from master process
  – Performs computation
  – Sends results to master
calculations on 2-dimensional array elements: solution 2

find out if I am MASTER or WORKER

if I am MASTER

    do until no more jobs
        if request send to WORKER next job
            else receive results from WORKER
        end do

else if I am WORKER

    do until no more jobs
        request job from MASTER
        receive from MASTER next job
        calculate array element: \( a(i,j) = fcn(i,j) \)
        send results to MASTER
    end do

endif
References

1. Introduction to Parallel Computing [Link](https://computing.llnl.gov/tutorials/parallel_comp/ #MemoryArch)
2. Intro to Parallel Programming. Lesson 2, pt. 1- Shared Memory and threads [Link](http://www.youtube.com/watch?v=6sL4C2SwM)
3. Intro to Parallel Programming. Lesson 2, pt. 2- Shared Memory and threads [Link](http://www.youtube.com/watch?v=ydG8cOzjL)
4. Intro to Parallel Programming. Lesson 2, pt. 3- Shared Memory and threads [Link](http://www.youtube.com/watch?v=403LWbrA5oU)
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<td>(Adam Belloum, UvA)</td>
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